

**PCC #:** \_\_\_\_\_

**BILL TO:** \_\_\_\_\_

**ADDRESS:** \_\_\_\_\_

\_\_\_\_\_

**SHIP TO:**  SAME AS BILLING \_\_\_\_\_

**ADDRESS:** \_\_\_\_\_

\_\_\_\_\_

**SHIPPING:**  GROUND (FXGD)  STANDARD 2 DAY (FX2D)  
 OVERNIGHT:  PRIORITY (FX1D)  1st OVERNIGHT (FX1A)  
 OTHER: \_\_\_\_\_

**CLINICIAN:** \_\_\_\_\_

**CELL #:** \_\_\_\_\_

**PATIENT ID:** \_\_\_\_\_

**HEIGHT:** \_\_\_\_\_ **WEIGHT:** \_\_\_\_\_ **AGE:** \_\_\_\_\_

**DIAGNOSIS:** \_\_\_\_\_ **AFFECTED SIDE (Check One):**  
 LEFT  RIGHT

**NG ENCOUNTER #:** \_\_\_\_\_

**MEASUREMENT DATE:** \_\_\_\_\_

**IN-OFFICE REQUEST DATE & TIME:** \_\_\_\_\_

PROJECT NEWTON (Credit applied on prior auth. denial, details on One Hanger)

**HFN:**  ANAHEIM  PHOENIX

OPPOSITIONAL  BODY POWERED  EXTERNAL POWERED

**TYPE OF DEVICE:** \_\_\_\_\_ **LAMINATION/GLOVE COLOR:** \_\_\_\_\_

SOCKET	
<b>STANDARD</b>	<b>OPTIONS</b>
<ul style="list-style-type: none"> <li>Flexible socket</li> </ul>	<input type="checkbox"/> Custom silicone socket <input type="checkbox"/> Lamination over socket <input type="checkbox"/> Laminated & removable <input type="checkbox"/> Detailed in notes section

FRAME LAMINATION	
<b>STANDARD</b>	<b>OPTIONS</b>
<ul style="list-style-type: none"> <li>Laminated, 6 layers Nyglass</li> <li>Carbon tape at wrist</li> <li>2 finishing layers</li> </ul>	<input type="checkbox"/> Carbon lamination (1 Carbon, 1 Nyglass, 1 Carbon) <input type="checkbox"/> Carbon tape throughout <input type="checkbox"/> Printed material as final

ALIGNMENT	
<b>STANDARD</b>	<b>OPTIONS</b> (changes from test fit)
<ul style="list-style-type: none"> <li>Follow test socket</li> </ul>	<input type="checkbox"/> Detailed in notes section

HARNES & CABLING (BODY POWERED SYSTEMS)	
<b>STANDARD</b>	<b>OPTIONS</b>
<ul style="list-style-type: none"> <li>Spectra with Teflon</li> <li>Wrist driven</li> </ul>	<input type="checkbox"/> Fig 9 Harness <input type="checkbox"/> No cabling requested <input type="checkbox"/> Detailed in notes section

**ELECTRONICS (EXTERNAL POWERED SYSTEM)**

**Control system:**  Otto Bock  Motion Control  Steeper  Touch Bionics  COAPT  Other: \_\_\_\_\_

Dual Site  Single Site

**Electrodes:**

OB  Steeper  
 Touch  Other  
 Motion Control  
 Standard  Silicone Apron  Remote Style

Switch/Linear Pot (detail below)

Int Battery  Ext Battery  
 LTI  Motion Control  Other  
 OB  IBT  
 Touch  Steeper

**Capacity:**  Std  Small  Large

**NOTES**

## TURNAROUND TIMES

To review current projected turnaround times for fabrication sites visit the [Daily HFN Capacity Webpage](#).